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# Convex Storage Loss Modeling for Optimal Energy Management

#### Pierre Haessig, Jesse James Prince Agbodjan, Romain Bourdais, Hervé Guéguen

CentraleSupélec (campus de Rennes) - IETR

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http://pierreh.eu

pierre.haessig@centralesupelec.fr

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- 2. Convex storage modeling
  - Generic storage model
  - Limitation of the linear loss model
  - Relaxation of storage losses
- 3. Panorama of storage loss models
  - Overview of loss models
  - Existing models
  - Our contribution
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## Energy management (EM) is often optimization based

EM = control of the power flows in a system with *storages* 



Control objective:

- Minimizing a criterion (economical, ecological...)
- Satisfaying constraints (e.g. storage bounds)

EM is often based on *online* optimization (e.g. MPC)  $\rightarrow$  optimization should be 100% reliable  $\rightarrow$  **convex** 

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Convex optimization problems can be solved reliably





#### Conditions this optimization to be convex

Convex objective J, convex ineq. func. g, linear eq. func. h

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Convex storage modeling

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# Generic storage model

Storage dynamics with losses is *linear*:

$$E_b(k+1) = E_b(k) + (P_b(k) - P_{loss})\Delta_t$$

 $\rightarrow$  Convexity of the storage model depends on the *convexity of the loss expression* 



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# Generic storage model

Storage dynamics with losses is *linear*:

$$E_b(k+1) = E_b(k) + (P_b(k) - P_{loss})\Delta_t$$

 $\rightarrow$  Convexity of the storage model depends on the *convexity of the loss expression* 

Now, what choice of loss expression:  $P_{loss} = ?$ 

- Convex for efficient optimization
- and also physically realistic?



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# Linear loss model: very limiting

Linear expression is the only *genuine* convex model:

$$P_{loss} = p_0 + c_P P_b + c_E E_b$$

Lossless storage  $(P_{loss})$  is the popular special case

### Coefficient meaning:

- *p*<sub>0</sub>: constant self-discharge
- $c_E$ : self-discharge proportional to energy level
- *c<sub>P</sub>*: physically *not meaningful*

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#### Coefficient meaning:

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#### Limitation

Unfortunately, many simple expressions like  $P_{loss} = P_b^2$  are *not convex* 

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# Relaxation of storage losses

#### Key idea (widely used in literature)

Relax the equality constraint (losses = some expression) to an inequality (losses  $\geq$  some expression).

 $\rightarrow$  This allows using *any convex expression* for losses

Generic loss formulation (assuming a dependency on storage power and energy):

 $P_{loss} \geq g(P_b, E_b)$ 

where g means any *convex* function.

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### Exactness of the relaxation of losses

Although losses relaxed as  $P_{loss} \ge g(P_b, E_b)$ , it is expected that, at the optimum, the inequality will be *tight*.

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### Exactness of the relaxation of losses

Although losses relaxed as  $P_{loss} \ge g(P_b, E_b)$ , it is expected that, at the optimum, the inequality will be *tight*.

#### Heuristic justification: "Positive price argument"

If the incremental cost of wasting energy is *positive*, then at the optimum, no energy should be wasted.

Otherwise (negative energy price), there can be an *artificial excess* of wasted energy (excess:  $P_{loss} - g > 0$ ).

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A few sets of sufficient conditions were reported, but:

- application specific
- cannot always be checked *ex-ante*
- o conditions are sufficient, but not necessary

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# Possibilities for loss expressions

Existing convex loss expressions (beyond linear):

- Piecewise-linear-in-*P* (i.e. **constant efficiency**): Physics-free, widespread usage
- Quadratic-in-*P*: approx. Joule heating (*r*.*I*<sup>2</sup>)
- Quadratic-in-*P* over linear-in-*E*  $(P^2/E)$ : approx. Joule heating in a capacitor

Our proposition: the "convex monomial loss model" ( $\sim P^a/E^b$ )

One continous family of nonlinear convex loss model

- parametrized by 4 (or 8) real coefficients: suitable for *model fitting* to experimental loss data
- o contains all existing models as special cases

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### Piecewise-linear-in-*P* loss model

Loss expression:

$$g(P_b, E_b) = c_+ P_b^+ + c_- P_b^-$$

with  $P_b^+$  and  $P_b^-$ : positive and neg. parts of  $P_b$ Property: physics-free



This loss model corresponds to the ubiquitous **constant efficiency** storage model\*:

$$E_b(k+1) \le E_b(k) + (\eta_+ P_b^+ + P_b^-/\eta_-)\Delta_t$$

with  $\eta_+ = 1 - c_+$  and  $\eta_- = 1/(1 + c_-)$ 

(\*) this model is normally written with "=", but it is still a relaxation, because variables  $P_b^+$ ,  $P_b^-$  are not exclusive unless imposed (MILP)

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# Quadratic-in-P loss model

Loss expression:

$$g(P_b, E_b) = \rho . P_b^2$$

Property: inspired by Joule heating



Correspondence to Joule heating in a circuit:  $\rho = r/v_0^2$ 



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# Quadratic-in-P loss model

Loss expression:

$$g(P_b, E_b) = \rho . P_b^2$$

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Correspondence to Joule heating in a circuit:  $\rho = r/v_0^2$ 

#### Idea to generalize the quadratic model

Because  $v_0$  and r typically depend on the energy level (*SoE*), search for a *separable* loss model with  $\rho(E_b)$ 



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### Contribution: the "Convex monomial loss model"

Loss expression (symmetric charge/discharge case):



Convex with  $a \ge 1, b \ge 0$  and  $b \le a - 1$ 

Examples:

- Quad-in- $P(a = 2) \rightarrow b \in [0, 1]$ , e.g.  $P^2/E$  (capacitor)
- PWL-in- $P(a = 1) \rightarrow b = 0 \rightarrow No \text{ SoE effect allowed!}$

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Contri	ibution: the "	Convex monomial	loss model"	

If charge/discharge asymmetry is wanted/needed

Loss expression:

$$g(P_b, E_b) = c_+ rac{(P_b^+)^{a_+}}{|E_b - e_+|^{b_+}} + c_- rac{(P_b^-)^{a_-}}{|E_b - e_-|^{b_-}}$$

A split between positive and negative parts of the power, like the PWL-in-*P* model.

(needed to implement the absolute value (a = 1) with a Linear Program)

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### Application: storage for grid-connected production



Optimization objective: energy sold to grid at price cgrid

$$\max C_{grid} = \sum_{k=1}^{K} c_{grid}(k) . P_{grid}(k) \Delta_t$$

# Scenario description: production shifting

Parameters: 2 hours ( $K = 20, \Delta_t = 0.1 \text{ h}$ ),  $E_{rated} = 1 \text{ kWh storage}$ 

- 1. 1<sup>st</sup> hour: prod.  $P_{prod} = 1 \text{ kW}$  and *low* price  $c_{grid} = 0.1 \text{ }/\text{kWh}$
- 2. 2<sup>nd</sup> hour: *zero* production and *high* price  $c_{grid} = 0.2 \notin kWh$

Interpretation

Storage can shift the production to the high price hour

#### Experiment objective

See the effect of the loss model on the charge/discharge profile

Remark: All loss models calibrated for same 80% round-trip storage efficiency on the experiment

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#### Production shifting experiment Case 1: Lossless storage



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### Production shifting experiment Case 2: PWL-in-P model



Losses reduce the gain, but no other effect on the profile

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#### Production shifting experiment Case 3: Quadratic-in-*P* model



Quadratic losses smooth out the charge/discharge power

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### Production shifting experiment Case 4a: P<sup>2</sup>/E model (supercapacitor)



Discharge power is reduced at low SoE

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#### **Production shifting experiment** Case 4b: $P^2/E$ model (supercapacitor), 75% round-trip efficiency



Charging reduced at low SoE, energy given away to the grid

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Tools				

Optimization results obtained by:

- describing optimization problems in Julia
- o using the JuMP package https://jump.dev/
- optimization solvers: Ipopt (NLP) and ECOS (LP, SOCP)

#### Results are open source

The complete code is available in a Jupyter notebook https://github.com/pierre-haessig/convex-storage-loss

(including one example where the relaxation fails: negative energy price)

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# Conclusion

### Contribution:

- Unified description of storage loss relaxation (linear & nonlinear cases)
- One loss model to bind them all

#### Significance

Better loss models unleash more realistic storage trajectories



# Conclusion

### Contribution:

- Unified description of storage loss relaxation (linear & nonlinear cases)
- One loss model to bind them all

### Significance

Better loss models unleash more realistic storage trajectories

#### Future work:

 Characterize the worst-case amount of artificially wasted energy, when the relaxation fails (negative energy price)

More details in a submitted conf. paper, soon available on HAL.





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